# Moore-Penrose Generalized Inverse to Kronecker Product Matrix Boundary Value Problems 

Appa Rao B.V, T.S.Rao


#### Abstract

This paper deals with the existence-uniqueness to Kronecker product (KP) 3- point boundary value problems(TBVP) for the first order linear system as well as nonlinear matrix differential equations with the help of Moore-Penrose generalized inverse and Banach fixed point theory.


Keywords: Existence-uniqueness, Moore-Penrose generalized inverse, Rectangular matrices.

## I. INTRODUCTION

The importance of system of differential equations and their occurrence in many physical problems are well known. Many authors[ [4]-[6]\&[11]] have studied the problems of existence-uniqueness to two and 3 - point boundary value problems(BVP's) for the first order matrix system of differential equations.
Here we focus our attention to KPTBVP associated with the system

$$
\begin{equation*}
(A(t) \otimes B(t)) x^{\prime}(t)+(C(t) \otimes D(t)) x(t)=g(t) \tag{1.1}
\end{equation*}
$$

where

$$
A(t), B(t)) \in C^{2}[a, c]
$$ and

$C(t), D(t)) \in C^{1}[a, c]$. A, C are rectangular matrices of order $m \times n . \mathrm{B}, \mathrm{D}$ are rectangular matrices of order $p \times q$ and $g(\mathrm{t})$ is a column mp- vector whose components are in C1[a, c], satisfying
$\left(L_{1} \otimes M_{1}\right) x(a)+\left(L_{2} \otimes M_{2}\right) x(b)+\left(L_{3} \otimes M_{3}\right) x(c)=\beta$,
where Lj 's and Mj 's $(\mathrm{j}=1,2,3)$ are $n$th and $q$ th order square matrices respectively and $\beta$ is a column nq-vector.

[^0]© The Authors. Published by Blue Eyes Intelligence Engineering and Sciences Publication (BEIESP). This is an open access article under the CC-BY-NC-ND license http://creativecommons.org/licenses/by-nc-nd/4.0/

The results of this paper are established under the assumptions, when $(A(t) \otimes B(t))$ is $m p \times n q \quad$ matrix, $(C(t) \otimes D(t))$ is in the column space of $(A(t) \otimes B(t))$ and Lj 's and Mj 's $(\mathrm{j}=1,2,3)$ are non-singular square matrices.
Recently many authors [[2],[3],[9] and [10]] have studied the applications of generalized inverses to BVPs associated with the system of first order differential equations. The rest of the paper is is as follows: mainly in 2nd section we obtain some fundamental results on generalized inverses, KP of matrices and BVPs.

In section 3 we investigate the existence- uniqueness of solutions associated with TPBVPs (1.1), Boundary condition(B.C)(1.2). The Green's function or matrix as well as associated Green's function or matrix properties are developed with the help of uniqueness property of the Moore-Penrose generalized inverse. Further results of existence and uniqueness of solutions of KP non-linear TPBVPs are presented in section 4.
$a \leq t h C_{\text {situation differs when ' } g \text { ' is non-linear and the }}$ boundary conditions are non-homogeneous. We obtain the criteria for existence and uniqueness to KPTBVP associated with the nonlinear system

$$
\begin{equation*}
(A \otimes B) x^{\prime}+(C \otimes D) x=g(t, x), \quad \mathrm{a} \leq \mathrm{t} \leq \mathrm{c} \tag{1.3}
\end{equation*}
$$

where $\mathrm{A}, \mathrm{B}, \mathrm{C}$ and D are stated as earlier and $g(t, x(t)) \in C\left([a, c] \times R^{m p}\right)$
satisfying(1.2). These results are established under the assumption that the related homogeneous boundary value problems. $(g(t, x(t))=0, \beta=0)$ has only the trivial solution. These results depend on Banach fixed point theorem and Green's matrix.

## II. Preliminaries

In this paper we assume that the reader is familiar with fundamental concepts of KP matrices. In this section we develop some basic results relating to generalized inverses,
Here we denote regular inverse of a matrix P by P-1 and its Moore-Penrose generalized inverse by $\mathrm{P}+$
Definition 2.1 [8]. Let $P(t) \in R^{m \times n}$. The $n \times m$ matrix $\mathrm{P}^{+}$is said to be the Moore-Penrose generalized inverse of P , if each of the following is satisfied.
(i) $\mathrm{PP}^{+} \mathrm{P}=\mathrm{P}$
(ii) $\mathrm{P}^{+} \mathrm{PP}^{+}=\mathrm{P}^{+}$
(iii) $\left(\mathrm{PP}^{+}\right)^{+}=\mathrm{PP}^{+}$

## Moore-Penrose Generalized Inverse to Kronecker Product Matrix Boundary Value Problems

(iv) $\left(\mathrm{P}^{+} \mathrm{P}\right)^{+}=\mathrm{P}^{+} \mathrm{P}$

Definition 2.2 A matrix $B(t)$ is said to be column space of $A(t)$ if there exists a square matrix $K(t)$ such that $B(t)=A(t) K(t)$.
Result 2.1 Suppose the matrices $\mathrm{C}(\mathrm{t})$ and $\mathrm{D}(\mathrm{t})$ are in the column space of $\mathrm{A}(\mathrm{t})$ and $\mathrm{B}(\mathrm{t})$ respectively, then $(C(t) \otimes D(t))$ is in the column space of $(A(t) \otimes B(t))$.

Proof: Since $C(t), D(t)$ is in the column space of the rectangular matrices $\mathrm{A}(\mathrm{t}), \mathrm{B}(\mathrm{t})$ respectively, then there exist square matrices $K_{1}(t), K_{2}(t)$ such that $C(t)=A(t) K_{1}(t)$ and $D(t)$ $=B(t) K_{2}(t)$.

Consider the Kronecker product matrix

$$
\begin{aligned}
(C(t) \otimes D(t)) & \left.=A(t) K_{1}(t)\right) \otimes B(t) K_{2}(t) \\
& =(A(t) \otimes B(t))\left(K_{1}(t) \otimes K_{2}(t)\right)
\end{aligned}
$$

Thus $(C(t) \otimes D(t)) \quad$ is in the column space of $(A(t) \otimes B(t))$.

Consider the equation

$$
\begin{equation*}
P y=q \tag{2.1}
\end{equation*}
$$

where $P(t) \in R^{m \times n}, m \geq n$.
Theorem 2.1. [12]
a) The following statements are equivalent:
(i) equation(2.1) is consistent
(ii) $\mathrm{PP}^{+} \mathrm{q}=\mathrm{q}$
(iii)Rank $\mathrm{P}=\operatorname{rank}[\mathrm{P} ; \mathrm{q}]$ i.e., q is the linear combination of columns of P
b)The solution, if it exists is unique if and only if $P$ has full $\operatorname{rank}(\operatorname{rank} \mathrm{P}=\mathrm{n})$. In fact the general solution is given by

$$
\begin{equation*}
\mathrm{y}=\mathrm{P}^{+} \mathrm{q}+\left(\mathrm{I}-\mathrm{P}^{+} \mathrm{P}\right) \mathrm{z} \tag{2.2}
\end{equation*}
$$

where $Z \in R^{n}$ is arbitrary. The unique least squares solution is $y=P^{+} q$.
Result 2.2[1] The equation

$$
\begin{equation*}
\mathrm{PY}=\mathrm{Q} \tag{2.3}
\end{equation*}
$$

is consistent if and only if $\left[\mathrm{I}_{\mathrm{m}}-\mathrm{PP}^{+}\right] \mathrm{Q}=\mathrm{O}$, where $\mathrm{P}, \mathrm{Y}$ and Q are matrices of order $m \times n, n \times m$ and $m \times m$ respectively.
Result 2.3[1] The equation (2.3) is consistent, then its general solution is of the form

$$
\mathrm{Y}=\mathrm{P}^{+} \mathrm{Q}+\left(\mathrm{I}_{\mathrm{n}}-\mathrm{P}^{+} \mathrm{P}\right) \mathrm{U}
$$

where U is an arbitrary matrix of order $n \times m$.

Result 2.4 [7] Any solution $x(t)$ of the system (1.1), the non-singular KP matrix $(A(t) \otimes B(t))$ is is of the form $\left.x(t)=X(t) L+X(t) \int_{a}^{t} X^{-1}(s) A^{-1}(s) \otimes B^{-1}(s)\right) g(s) d s$ Here the fundamental matrix $X(t)$ of the homogeneous equation associated with (1.1) and $L$ is a constant mp-vector.
Result 2.5 Let $\mathrm{A}^{+}(\mathrm{t}), \mathrm{B}^{+}(\mathrm{t})$ be the generalized inverses of A and $B$ respectively and suppose $(C(t) \otimes D(t))$ is in the column space of $(A(t) \otimes B(t))$ with

$$
(C(t) \otimes D(t))=(A(t) \otimes B(t))\left(K_{1}(t) \otimes K_{2}(t)\right) . \text { Then }
$$ the two systems

$$
\begin{equation*}
(A(t) \otimes B(t)) x^{\prime}(t)+(C(t) \otimes D(t)) x(t)=0 \tag{2.4}
\end{equation*}
$$

and
$x^{\prime}+\left(K_{1} \otimes K_{2}\right) x=\left[I_{n q}-\left(A^{+} \otimes B^{+}\right)(A \otimes B)\right] v$
are equivalent, where $v$ is any constant nq-vector.
Proof: Let $x_{1}$ be a solution of (2.5) then
$\left.x_{1}^{\prime}+K_{1} \otimes K_{2}\right) x_{1}=\left[I_{n q}-\left(A^{+} \otimes B^{+}\right)(A \otimes B)\right] v$
for some $v \in R^{n q}$.

$$
\begin{aligned}
(A \otimes B) x_{1}^{\prime} & +(A \otimes B)\left(K_{1} \otimes K_{2}\right) x_{1} \\
& =(A \otimes B)\left[I_{n q}-\left(A^{+} \otimes B^{+}\right)(A \otimes B)\right] v \\
& =0
\end{aligned}
$$

Hence $\left(A(\otimes B) x^{\prime}+(C \otimes D) x=0\right.$. We can prove the converse in a similar manner.

Remark2.6. In view of result 2.5 the linear system (2.1) is equivalent to
$x^{\prime}+\left(K_{1} \otimes K_{2}\right) x=h$
where
$h=\left(A^{+} \otimes B^{+}\right) g+\left[I_{n q}-\left(A^{+} \otimes B^{+}\right)(A \otimes B)\right] v$.
Theorem2.2 [4] The fundamental matrix X of the homogeneous equation

$$
\begin{equation*}
x^{\prime}(t)+\left(K_{1}(t) \otimes K_{2}(t)\right) x(t)=0 \tag{2.7}
\end{equation*}
$$

Then any solution (2.6) is of the form
$x=X L+X \int_{a}^{t} X^{-1}(s) h(s) d s$
where $L$ is a constant nq-vector.
Theorem 2.3 Let
$E=\left(L_{1} \otimes M_{1}\right) X(a)+\left(L_{2} \otimes M_{2}\right) X(b)+\left(L_{3} \otimes M_{3}\right) X(c)$
be the characteristic matrix for the homogeneous boundary value problem (2.7) associated with

$$
\begin{equation*}
\left(L_{1} \otimes M_{1}\right) x(a)+\left(L_{2} \otimes M_{2}\right) x(b)+\left(L_{3} \otimes M_{3}\right) x(c)=0 \tag{2.9}
\end{equation*}
$$

If rank $E=r$, then the index of compatibility of (2.9) is nq-r.
Note 2.1 In general the solution space of (2.4) does not constitute a finite dimensional space. This leads to the failure of classical methods for finding a solution to the equation (1.1).

## III. Kronecker product Linear BVP

Now we establish the existence and uniqueness of solutions to KTBVP (2.6), satisfying (1.2) under the assumption that the matrices Lj 's and Mj 's $(\mathrm{j}=1,2,3)$ are non-singular square matrices.

Theorem3.1 The fundamental matrix $\mathrm{X}(\mathrm{t})$ of (2.7), also assume that the homogeneous BVP (2.9) is incompatible. Then there- exists a unique solution $x(t)$ to the non-homogeneous BVP (1.1) , (1.2) is given by
$x=X E^{-1} \beta+\int_{a}^{c} G(t, s)\left[I_{n q}-\left(A^{+} A \otimes B^{+} B\right] v d s+\int_{a}^{c} H(t, s) g(s) d s\right.$
here E is the characteristic matrix, $\mathrm{G}(\mathrm{t}, \mathrm{s})$ is the Green's function and the associated Green's function $\mathrm{H}(\mathrm{t}, \mathrm{s})$ for the homogeneous BVP.
Proof: Any solution of (2.6) by using theorem 2.2 is of the form

$$
x=X L+X \int_{a}^{t} X^{-1}(s) h(s) d s
$$

where $\mathrm{X}(\mathrm{t})$ is defined earlier and L is a constant nq-vector and will be determined uniquely from the fact that $\mathrm{x}(\mathrm{t})$ must obey the B.C(1.2). Substituting the general form of $\mathrm{x}(\mathrm{t})$ in the boundary conditions(1.2), we have

$$
\begin{aligned}
& {\left[\left(L_{1} \otimes M_{1}\right) X(a)+\left(L_{2} \otimes M_{2}\right) X(b)+\left(L_{3} \otimes M_{3}\right) X(c)\right] \mathrm{L}} \\
& \quad+\left(L_{2} \otimes M_{2}\right) X(b) \\
& \quad \times \int_{\mathrm{a}}^{\mathrm{b}} \mathrm{X}^{-1}(\mathrm{~s}) \mathrm{h}(\mathrm{~s}) \mathrm{ds}+\left(L_{3} \otimes M_{3}\right) X(c) \int_{\mathrm{a}}^{\mathrm{c}} \mathrm{X}^{-1}(\mathrm{~s}) \mathrm{h}(\mathrm{~s}) \mathrm{ds}=\beta
\end{aligned}
$$

and thus

$$
\begin{gathered}
\mathrm{L}=\mathrm{E}^{-1} \beta-E^{-1}\left(L_{2} \otimes M_{2}\right) X(b) \\
\times \int_{\mathrm{a}}^{\mathrm{b}} \mathrm{X}^{-1}(\mathrm{~s}) \mathrm{h}(\mathrm{~s}) \mathrm{ds}
\end{gathered}
$$

$$
-\mathrm{E}^{-1}\left(L_{3} \otimes M_{3}\right) X(c) \int_{\mathrm{a}}^{\mathrm{c}} \mathrm{X}^{-1}(\mathrm{~s}) \mathrm{h}(\mathrm{~s}) \mathrm{ds}
$$ where ' $E$ ' is defined earlier. Substituting ' $L$ ' in the solution form gives

$$
\begin{aligned}
& x(t)=X(t) E^{-1} \beta+\mathrm{X}(\mathrm{t}) \int_{\mathrm{a}}^{\mathrm{t}} \mathrm{X}^{-1}(\mathrm{~s}) \mathrm{h}(\mathrm{~s}) \mathrm{ds} \\
& \quad-X(t) E^{-1}\left(L_{2} \otimes M_{2}\right) X(b) \\
& \times \int_{\mathrm{a}}^{\mathrm{b}} \mathrm{X}^{-1}(\mathrm{~s}) \mathrm{h}(\mathrm{~s}) \mathrm{ds} \\
& \quad-X(t) E^{-1}\left(L_{3} \otimes M_{3}\right) X(c) \int_{\mathrm{a}}^{\mathrm{c}} \mathrm{X}^{-1}(\mathrm{~s}) \mathrm{h}(\mathrm{~s}) \mathrm{ds}
\end{aligned}
$$

now rewriting the integrals using the fact that
$X(t)=X(t) E^{-1} E=X(t) E^{-1}\left[\left(L_{1} \otimes M_{1}\right) X(a)\right.$
$\left.+\left(L_{2} \otimes M_{2}\right) X(b)+\left(L_{3} \otimes M_{3}\right) X(c)\right]$
and substituting the value of

$$
h=\left(A^{+} \otimes B^{+}\right) g+\left[I_{n q}-\left(A^{+} \otimes B^{+}\right)(A \otimes B)\right] v
$$

We get

$$
\begin{aligned}
& x=X E^{-1} \beta \\
& +\int_{a}^{c} G(t, s)\left[I_{n q}-\left(A^{+} A \otimes B^{+} B\right] v d s+\int_{a}^{c} H(t, s) g(s) d s\right.
\end{aligned}
$$

where

$$
\underset{t \in[a, b]}{G(t, s)}=\left\{\begin{array}{r}
X(t) E^{-1}\left(L_{1} \otimes M_{1}\right) X(a) X^{-1}(s) \\
a<\mathrm{s}<\mathrm{t} \leq \mathrm{b}<\mathrm{c} \\
-X(t) E^{-1}\left[\left(L_{2} \otimes M_{2}\right) X(b)\right. \\
\left.+\left(L_{3} \otimes M_{3}\right) X(c)\right] X^{-1}(s) \\
\mathrm{a} \leq \mathrm{t}<\mathrm{s}<b<\mathrm{c} \\
-X(t) E^{-1}\left(L_{3} \otimes M_{3}\right) X(c) X^{-1}(s) \\
\mathrm{a} \leq \mathrm{t}<\mathrm{b}<\mathrm{s}<\mathrm{c}
\end{array}\right.
$$

$$
\underset{t \in[b, c]}{G(t, s)}=\left\{\begin{array}{c}
X(t) X^{-1}(\mathrm{~s})-X(t) E^{-1}\left(L_{3} \otimes M_{3}\right) X(c) X^{-1}(\mathrm{~s}), \\
\mathrm{a}<\mathrm{b}<\mathrm{s}<\mathrm{t} \leq \mathrm{c} \\
-X(t) E^{-1}\left(L_{3} \otimes M_{3}\right) X(c) X^{-1}(\mathrm{~s}), \\
\mathrm{a}<\mathrm{b} \leq \mathrm{t}<\mathrm{s}<\mathrm{c} \\
X(t) E^{-1}\left(L_{1} \otimes M_{1}\right) X(a) X^{-1}(\mathrm{~s}), \\
\mathrm{a}<\mathrm{s}<\mathrm{b}<\mathrm{t} \leq \mathrm{c}
\end{array}\right.
$$

(ii) The formal solution $G(t, s)$ of the homogeneous BVP(2.9). The Green's function not satisfies original solution because of the discontinuity at $t=s$.
(iii) The properties (i) and (ii) is unique for the Green's function $G(t, s)$.

Theorem 3.3 Associated Green's function $H(t, s)$ has the following properties;
(i) $H(t, s)$ as a function of ' $t$ ' with fixed ' $s$ ' has continuous derivatives everywhere except at $t=s$. At the point $t=s, H(t, s)$ has jump discontinuity of unit magnitude and is given by

$$
H\left(s^{+}, s\right)-H\left(s^{-}, s\right)=I_{n q}
$$

(ii) The formal solution $H(t, s)$ of the homogeneous $\operatorname{BVP}(2.9) . H(t, s)$ fails to be actual solution because of the discontinuity at $t=s$.
(iii)The properties (i) and (ii) of $H(t, s)$ satisfying is unique.
Remark 3.1 H(t, s) is also unique because the Moore-Penrose generalized inverse if it exists is unique.

## IV. Kronecker Product Non-linear boundary VALUE PROBLEMS

In this section we obtain existence - uniqueness of solutions of KP non-linear TPBVP (1.3), (1.4). Here the function $g(t, x)$ assume that it satisfies Lipschitz condition

$$
\begin{equation*}
|g(t, x)-g(t, z)| \leq M|x-z|, \forall(t, x),(t, z) \in[a, c] \times R^{n q \times n q}, \tag{4.1}
\end{equation*}
$$

here M is a nonnegative constant and $|$.$| denotes the usual$ norm as in the text book Cole [4].

Note 4.1 In view of result 2.5, the non-linear system (1.3) is equivalent to
$x^{\prime}+\left(K_{1} \otimes K_{2}\right) x=h(t, x)$
where
$h(t, x(t))=\left(A^{+} \otimes B^{+}\right) g+\left[I_{n q}-\left(A^{+} A \otimes B^{+} B\right)(t)\right] v$, v is a nq-column vector.
Lemma 4.1 The fundamental matrix $X(t)$ of the homogeneous equation (2.7), then the solution of (4.2) is given by

$$
G\left(s^{+}, s\right)-G\left(s^{-}, s\right)=I_{n q} .
$$

$$
x=X L+X \int_{a}^{t} X^{-1}(s) h(s, x(s)) d s
$$

where $L$ is a constant nq-column vector.
Lemma 4.2 The fundamental matrix $X(t)$ of the homogeneous equation (2.7), then the vector $\Psi(\mathrm{t})$ defined by $\Psi(\mathrm{t})=\mathrm{X}(\mathrm{t}) \mathrm{E}^{+} \beta$ is also a solution for the equation (2.7).

Theorem 4.1 Suppose that the homogeneous boundary value problem is in compatible and $\mathrm{g}(\mathrm{t}, \mathrm{x}(\mathrm{t})$ ) satisfies Lipschitz condition (4.1), then if

$$
M N \max _{t \in[a, c]} \int_{a}^{c}\left|G_{1}(t, s) d s\right|<1
$$

the problem(4.2) satisfying(1.2) has one and only one solution, where $G_{1}(t, s)$ is the Green's matrix for the corresponding homogeneous BVP and

$$
N=\max _{t \in[a, c]}\left|(A \otimes B)^{+}\right|
$$

Proof: From lemma 4.1 the solution of (4.2) is given by (4.3) and $X(t), L$ are defined earlier also must satisfy the B.Cs (1.2). Substituting the general form of $\mathrm{x}(\mathrm{t})$ in the boundary conditions(1.2), we have

$$
\begin{aligned}
& {\left[\left(L_{1} \otimes M_{1}\right) X(a)+\left(L_{2} \otimes M_{2}\right) X(b)+\left(L_{3} \otimes M_{3}\right) X(c)\right] L} \\
& ] L^{X \in C^{n q}[a, c] \text { with the norm }\|x(t)\|=\max _{t \in[a, c]}|x(t)| \text {. Hence }-2 .} \\
& t \in[a, c]
\end{aligned}
$$

$$
\begin{aligned}
& +\left(L_{2} \otimes M_{2}\right) X(b) \\
& \times \int_{\mathrm{a}}^{\mathrm{b}} \mathrm{X}^{-1}(\mathrm{~s}) \mathrm{h}(\mathrm{~s}, \mathrm{x}(\mathrm{~s})) \mathrm{ds}+\left(L_{3} \otimes M_{3}\right) X(c) \\
& \times \int_{\mathrm{a}}^{\mathrm{c}} \mathrm{X}^{-1}(\mathrm{~s}) \mathrm{h}(\mathrm{~s}, \mathrm{x}(\mathrm{~s})) \mathrm{ds}=\beta
\end{aligned}
$$

$$
\begin{align*}
E L= & \beta-\left(L_{2} \otimes M_{2}\right) X(b) \\
& \times \int_{a}^{b} \mathrm{X}^{-1}(\mathrm{~s}) \mathrm{h}(\mathrm{~s}, \mathrm{x}(\mathrm{~s})) \mathrm{ds}-\left(L_{3} \otimes M_{3}\right) X(c) \\
& \times \int_{\mathrm{a}}^{\mathrm{c}} \mathrm{X}^{-1}(\mathrm{~s}) \mathrm{h}(\mathrm{~s}, \mathrm{x}(\mathrm{~s})) \mathrm{ds}=\eta \tag{4.5}
\end{align*}
$$

Suppose the equation (4.5) in ' L ' is consistent, then $\left(\mathrm{I}_{\mathrm{nq}}-\mathrm{E}^{+} \mathrm{E}\right)=\mathrm{O}$ and the unique least square solution ' L ' is given by $\mathrm{L}=\mathrm{E}^{+} \eta$. Substituting the value of ' L ' in the solution of $\mathrm{x}(\mathrm{t})$ in the boundary conditions(1.2), we get

$$
x=X E^{+} \eta+X \int_{a}^{c} G_{1}(t, s) h(s, x) d s
$$

where

$$
\underset{\substack{  \tag{4.3}\\
G_{1}(t, a, b]}}{ }(t, s)\left\{\begin{array}{r}
X(t) E^{+}\left(L_{1} \otimes M_{1}\right) X(a) X^{-1}(\mathrm{~s}), \\
\mathrm{a}<\mathrm{s}<\mathrm{t} \leq \mathrm{b}<\mathrm{c} \\
-X(t) E^{+}\left[\left(L_{2} \otimes M_{2}\right) X(b)\right. \\
\left.+\left(L_{3} \otimes M_{3}\right) X(c)\right] X^{-1}(s), \\
\mathrm{a} \leq \mathrm{t}<\mathrm{s}<b<\mathrm{c} \\
-X(t) E^{+}\left(L_{3} \otimes M_{3}\right) X(c) X^{-1}(s), \\
\mathrm{a} \leq \mathrm{t}<\mathrm{b}<\mathrm{s}<\mathrm{c}
\end{array}\right.
$$

$$
\underset{\substack{  \tag{4.4}\\
G_{1}(t, b, c]}}{ }=\left\{\begin{array}{c}
X(t) X^{-1}(s) \\
-X(t) E^{+}\left(L_{3} \otimes M_{3}\right) X(c) X^{-1}(s) \\
\mathrm{a}<\mathrm{b}<\mathrm{s}<\mathrm{t} \leq \mathrm{c} \\
-X(t) E^{+}\left(L_{3} \otimes M_{3}\right) X(c) X^{-1}(s) \\
\mathrm{a}<\mathrm{b} \leq \mathrm{t}<\mathrm{s}<\mathrm{c} \\
X(t) E^{+}\left(L_{1} \otimes M_{1}\right) X(a) X^{-1}(s) \\
\mathrm{a}<\mathrm{s}<\mathrm{b}<\mathrm{t} \leq \mathrm{c}
\end{array}\right.
$$

Let $\mathrm{X}(\mathrm{t}) \mathrm{E}^{+} \beta=\Psi(\mathrm{t})$. The linear space ' J ' of functions
the linear space ' $J$ ' is a Banach space.
Now define the mapping $T: J \rightarrow J$ is

$$
T x=\int_{a}^{c} G_{1}(t, s) h(s, x) d s
$$

Then, if $u, w \in J$

## Moore-Penrose Generalized Inverse to Kronecker Product Matrix Boundary Value Problems

$$
\begin{aligned}
|T u(t)-T w(t)| & =\left|\int_{a}^{c} G_{1}(t, s) h(s, u(s)) d s-\int_{a}^{c} G_{1}(t, s) h(s, w(s)) d s\right| \\
& =\left|\int_{a}^{c} G_{1}(t, s)[h(s, u(s))-h(s, w(s))] d s\right| \\
& \leq \int_{a}^{c}\left|G_{1}(t, s)\right|\left|(A \otimes B)^{+}(s)\right||g(s, u(s))-g(s, w(s))| d s \\
& \leq M\left|(A \otimes B)^{+}\right|_{a}^{c}\left|G_{1}(t, s)\right||u(s)-w(s)| d s .
\end{aligned}
$$

Hence

$$
\|T u-T w\| \leq M N\|u-w\| \max _{t \in[\mathrm{a}, \mathrm{c}]} \int_{a}^{c}\left|G_{1}(t, s)\right| d s
$$

$\|T u-T w\| \leq \zeta\|u-w\|$,
where

$$
\zeta=M N \max _{\mathrm{t} \in[\mathrm{a}, \mathrm{c}]} \int_{a}^{c}\left|G_{1}(t, s)\right| d s<1
$$

Since $\zeta<1$, the mapping is contraction and hence by Banach fixed point theorem $\exists$ a unique solution to the BVP (4.2) with boundary condition

$$
\begin{equation*}
\left(L_{1} \otimes M_{1}\right) x(a)+\left(L_{2} \otimes M_{2}\right) x(b)+\left(L_{3} \otimes M_{3}\right) x(c)=0 \tag{4.6}
\end{equation*}
$$

By applying the above procedure to the BVP
$x^{\prime}+\left(K_{1} \otimes K_{2}\right) x=h(t, x+\psi)$,
and(4.6) a unique solution $x_{1}$ is constructed. Define $z=x_{1}+\Psi$, then z is a solution of (4.7) satisfying (4.6). Hence z is a unique solution to the BVP (4.2) with boundary condition (1.2).

Remark 4.1 Here $G_{1}(t, s)$ satisfies the usual properties of Green's matrix.

## REFERENCES

1. Ben-Israel A. and Gravil T N V, 1974, Generalized inverses theory and its applications, Wiley-Interscience, .
2. Campbell S L, 1980, Singular systems of differential equations, Pitman, London.
3. Campbell S L, 1982,Singular systems of differential equations-II, Pitman, London.
4. Cole R H, 1968, The theory of ordinary differential equations, ppelton-Century-Crafts.
5. Graham A, 1981,Kronecker Products and Matrix Calculus ; With Applications, Ellis Horwood Ltd. England.
6. Murty M S N,1987, Non linear three point boundary value problems associated with the system of first order matrix differential equations, Bull.Ins.Maths.Academia Sincica, 15(2), 243-249.
7. Murty K N, Prasad K R and Rao Y S, 1992,Kronecker product(multi) point boundary value problems-existence and uniqueness, Bull.Ins.Maths.Academia Sincica, 20(2), 83-95.
8. Murty M S N and Appa Rao B V, 2005, On three point boundary value problems for Quasi-linear systems, Jour. Indian, Acad.Math, 27(2), 245-251.
9. Murty M S N and Appa Rao B V,1998, Application of Moore-Penrose inverse to three point boundary value problems, Ranchi University Math. J. Vol.29, 1-9.
10. Murty M S N and Rao D R K S ,1991, Application of generalized inverse to two point boundary value problems, Bull.Ins.Maths.Academia Sincica, 19(3), 271-278.
11. Rao D R K S, Murty K N and Murty M S N,1982, On three point boundary value problems containing parameters, Bull.Ins.Maths.Academia Sincica, 10(3), 265-275.
12. Rao, B. V., \& Prasad, K. A. S. N. V. (2018). Existence of $\Psi$-bounded solutions for sylvester matrix dynamical systems on time scales. Filomat, 32(12), 4209-4219. doi:10.2298/FIL1812209R
13. Rao, B. V., \& Vara Prasad, K. A. S. N. (2016). Controllability and observability of sylvester matrix dynamical systems on time scales. Kyungpook Mathematical Journal, 56(2), 529-539. doi:10.5666/KMJ.2016.56.2.529
14. Uvah J A and Vastsala A S,1991, Monotone iterative technique for non-linear boundary value problems of first order differential systems with rectangular coefficients, J.Math. Anal.Appl, Vol.162, 482-493.

## AUTHORS PROFILE



Dr B V Appa Rao, Professor, Dept.of .Mathematics, having 26 years teaching and research experience for UG and PG Engineering programs. He obtained his PG(M.Sc) , M. Phil and Ph.D from ANU(Acharaya Nagarjuna University). Successfully guided one scholar for the award of Ph.D in dynamical systems and published 35 research publications.

Dr T.S.Rao, Associate professor, having 20 years of research and teaching experience for UG. He obtained his Ph.D from Koneru Lakshmaiah Educational Foundation. He published 12 research papers.


[^0]:    Manuscript published on 30 September 2019

    * Correspondence Author

    B V Appa Rao*, Professor, Department of Mathematics, Koneru Lakshmaiah Education Foundation, Vaddeswaram, Guntur, Andhra Pradesh, India - 522502. Email:bvardr2010@kluniversity.in
    T.S.Rao, Associate professor, Department of Mathematics, Koneru Lakshmaiah Education Foundation, Vaddeswaram, Guntur, Andhra Pradesh, India - 522502 Email:
    tagallamudi_me@kluniversity.in

